



# Safety Analysis of a CBTC System: A Rigorous Approach with Event-B

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- ≡ Feedback on the safety analysis conducted on the CBTC Octys, a RATP product.
- ≡ Characterized by a rigorous approach supported by lightweight use of formal methods.
- ≡ Output: safety analysis spanning a set of related documents that provide:
  - ▶ a logical argument establishing the safety properties guaranteed by Octys
  - ▶ a set of sufficient requirements (hypotheses)
  - ▶ hypotheses can be used as
    - rules for data validation on lines equipped with Octys
    - proof goals for sub-system designs
  - ▶ the argument builds a theory useful to guide future developments of Octys



≡ CBTC

- ▶ Generalities

- ▶ Octys

≡ Mathematically grounded safety analysis

≡ Elements of methodology

≡ Grounded safety analysis in action

≡ Example: Track circuits backup

≡ Lessons learnt and prospective



## ≡ Distributed system

- ▶ e.g. carborne controller, zone controller
- ▶ distribution of responsibilities varies according to CBTC

## ≡ Increase throughput

- ▶ reduce headway
- ▶ substitute failing interlocking devices

## ≡ Improve safety

- ▶ continuous spacing control
- ▶ passenger transfers

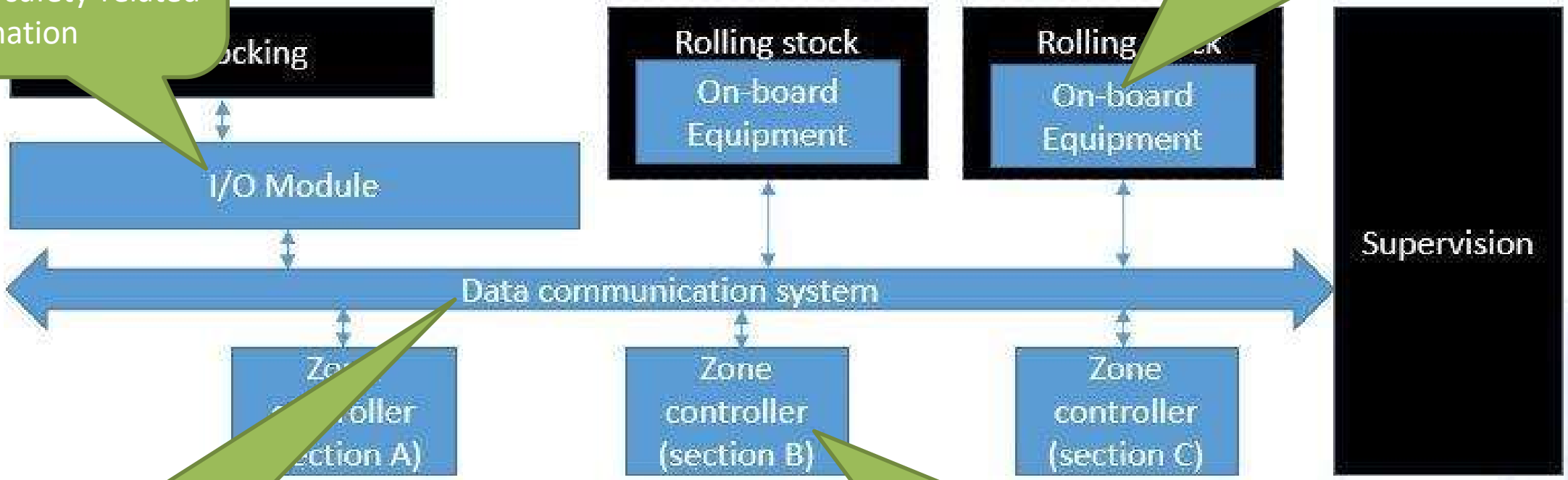
## ≡ Reduce wayside signaling costs



- ≡ Octys = Open Control of Trains, Interchangeable and Integrated System
  
- ≡ RATP modernization program for 13 metro lines with drivers.
  - ▶ brownfield deployment
  
- ≡ Specific challenges:
  - ▶ no disruption of service
  - ▶ multi-sourcing and interoperability
  
- ≡ Already deployed on several RATP lines
  - ▶ Multi-line and multi-vendor: suitable for a formal safety proof

- Interface zone controller with interlocking
- Treats safety-related information

- Estimate and send position (cartography, beacons, odometry)
- Calculate and control max speed from MAL



- Distributed among equipments
- Protocol comprises clock synchronization

- Track trains on the line (positions, interlocking sensors)
- Calculate and send MAL to equipped trains

≡ System operator – RATP:

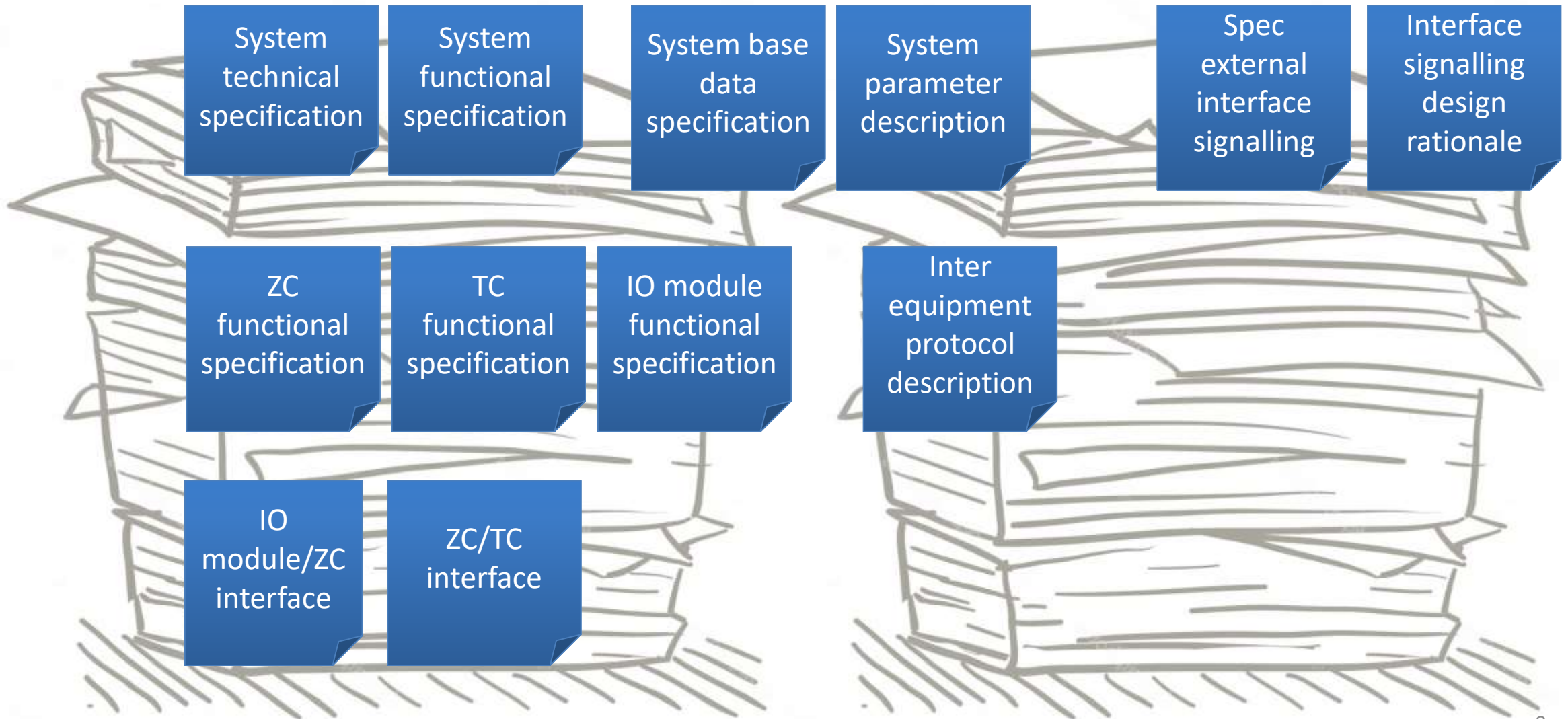
- ▶ 2-3 staff
- ▶ expertise in formal methods and railway systems

≡ Safety analysis team – ClearSy:

- ▶ 3-5 engineers
- ▶ expertise in formal methods
- ▶ different backgrounds (including railway systems)

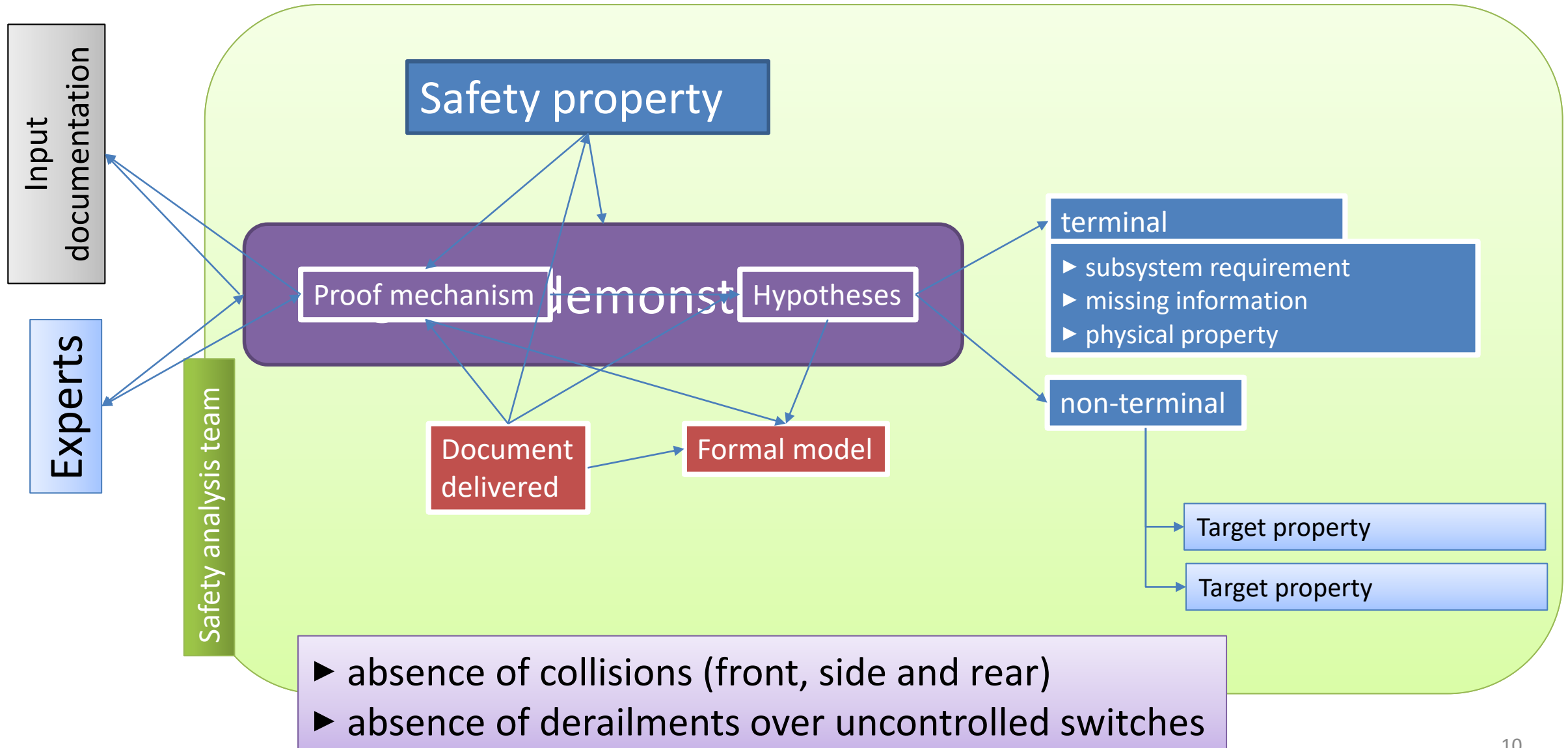
≡ Solution expert – Siemens:

- ▶ 1 staff with deep technical knowledge of Octys





- ≡ Monthly meetings, ad hoc communications by email and phone
  
- ≡ Discussion of specific Octys functionalities – presentation of analysis of properties
  - ▶ Discussion based on scenarios
    - Clarify understanding of functionalities
    - Focused technical questions
  - ▶ Presentation of safety analysis
    - Validation of hypotheses
    - Description and validation of proof mechanism
  
- ≡ Before meetings with partners, the safety analysis team makes internal presentations to consolidate the arguments.





- ≡ Each proof mechanism is validated with *tools*: Event-B and Atelier B.
- ≡ Event-B provides a computerized mathematical language to formalize systems.
- ≡ Event-B requires that the consistency and well-definedness of the formalization is proved using *pure logic and mathematical reasoning*.
  - ▶ Event-B has no built-in knowledge of railway systems or CBTCs
  - ▶ Each hypothesis needs to be thoroughly formalized with mathematical objects.
  - ▶ No reasoning shortcut (or error!) is possible.
- ≡ Atelier B is a toolset to write Event-B models and to perform all such proofs.
- ≡ *Beware*: Event-B is *not* a mean to *find* proof mechanisms.
  - ▶ But we find it useful for their consolidation and *necessary* for their verification.



- ≡ Octys is a CBTC for deployment on lines already equipped with an interlocking system.
- ≡ Neither the CBTC nor interlocking guarantee safety by itself.
  - ▶ Octys has not been designed to prevent front and side collisions, derailment on unlocked switches.
  - ▶ interlocking does not prevent rear collisions between equipped trains
- ≡ The safety analysis must take into account the interplay between the CBTC and interlocking.

≡ identify a protection zone for each kind of train

$$pz : TRAIN \rightarrow PZ$$

≡ such that each train stays in its protection zone by its braking forces:

$$\forall tr \cdot tr \in TRAIN \Rightarrow tr \subseteq pz(tr)$$

- define protection zone based on terrain objects
- model any possible terrain objects change as an evolution of protection zones

≡ no geometrical intersection between protection zones:

$$\forall tr_a, tr_b \cdot tr_a \in TRAIN \wedge tr_b \in TRAIN \wedge tr_a \neq tr_b \Rightarrow pz(tr_a) \cap pz(tr_b) = \emptyset.$$

≡ anti-collision property:

$$\forall tr_1, tr_2 \cdot tr_1 \in TRAIN \wedge tr_2 \in TRAIN \wedge tr_1 \neq tr_2 \Rightarrow tr_1 \cap tr_2 = \emptyset.$$

≡ in a protection zone, switches are locked:

- ▶ similar reasoning applies

≡ to model evolutions on concrete objects corresponding to protection zone, we formalize evolutions on protection zones.

≡ example: if the protection zone of train  $tr_1$  is extended by a track portion  $new$ :

$$pz(tr_1) \leftarrow pz(tr_1) \cup new$$

≡ then we have to argue that all the properties stated before still hold.

≡ For example

$$\forall tr_a, tr_b \cdot tr_a \in TRAIN \wedge tr_b \in TRAIN \wedge tr_a \neq tr_b \Rightarrow pz(tr_a) \cap pz(tr_b) = \emptyset.$$

≡ We have to prove :

$$\forall tr \cdot tr \in TRAIN \wedge tr \neq tr_1 \Rightarrow (pz(tr_1) \cup new) \cap pz(tr) = \emptyset.$$

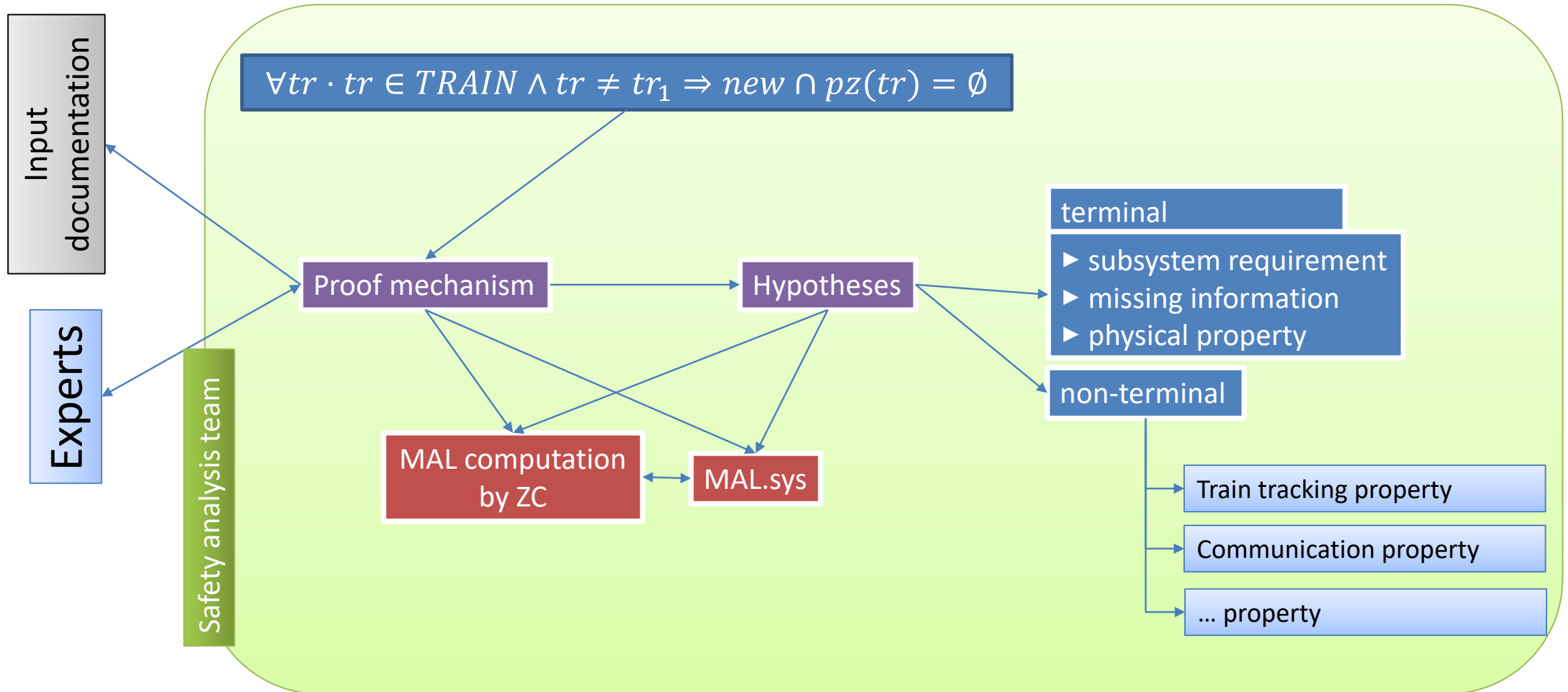
Since

$$\forall tr \cdot tr \in TRAIN \wedge tr \neq tr_1 \Rightarrow pz(tr) \cap pz(tr_1) = \emptyset,$$

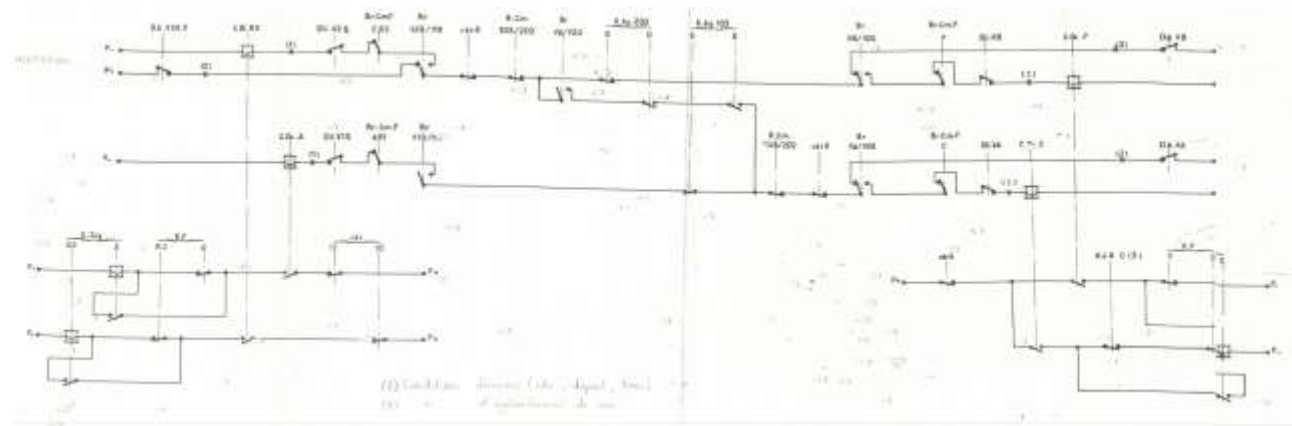
it is sufficient to prove :

$$\forall tr \cdot tr \in TRAIN \wedge tr \neq tr_1 \Rightarrow new \cap pz(tr) = \emptyset.$$

# Decomposition in action



- ≡ Initial plan: analyze all possible evolutions of protection zones regarding interlocking and CBTC functions
  - ▶ issue: access only to documentation of CBTC
  - ▶ sole hypothesis on interlocking: safe before deployment of CBTC
- ≡ Experience shows this approach requires exposing more details on interlocking, which we decided to avoid.
  - ▶ cost: interlocking circuits are complex devices
  - ▶ usability: we cannot forecast the interlocking circuits of lines where Octys will be deployed in the future







- ≡ Final argument: based on protection zones, as usual.
- ≡ Protection zones are given a precise semantics in terms of concrete objects (signals, train envelopes and rollback, etc.)
- ≡ All possible evolutions of these concrete objects are modelled as evolutions of protection zones
  - ▶ identify all properties on equipped trains that need proof
  - ▶ identify hypotheses on protection zones from interlocking
- ≡ Interlocking-related hypotheses on protection zones have to be verified by interlocking experts based on
  - ▶ properties of the CBTC we provide them
  - ▶ properties of interlocking these experts identify and verify

# Example: track circuit backup



« We delegate to interlocking experts the verification of interlocking hypotheses, providing them properties of the CBTC. »

≡ Octys includes functionalities altering interlocking inputs, e.g. *track circuit backup*.

≡ Track circuits are train detection devices.

≡ Top-level argument:

- ▶ safety properties are guaranteed by the existence of protection zones.
- ▶ requirement for interlocking: existence of such protection zones against
  - front and side collisions and
  - derailment on unlocked switches
  - rear collisions for non-equipped trains

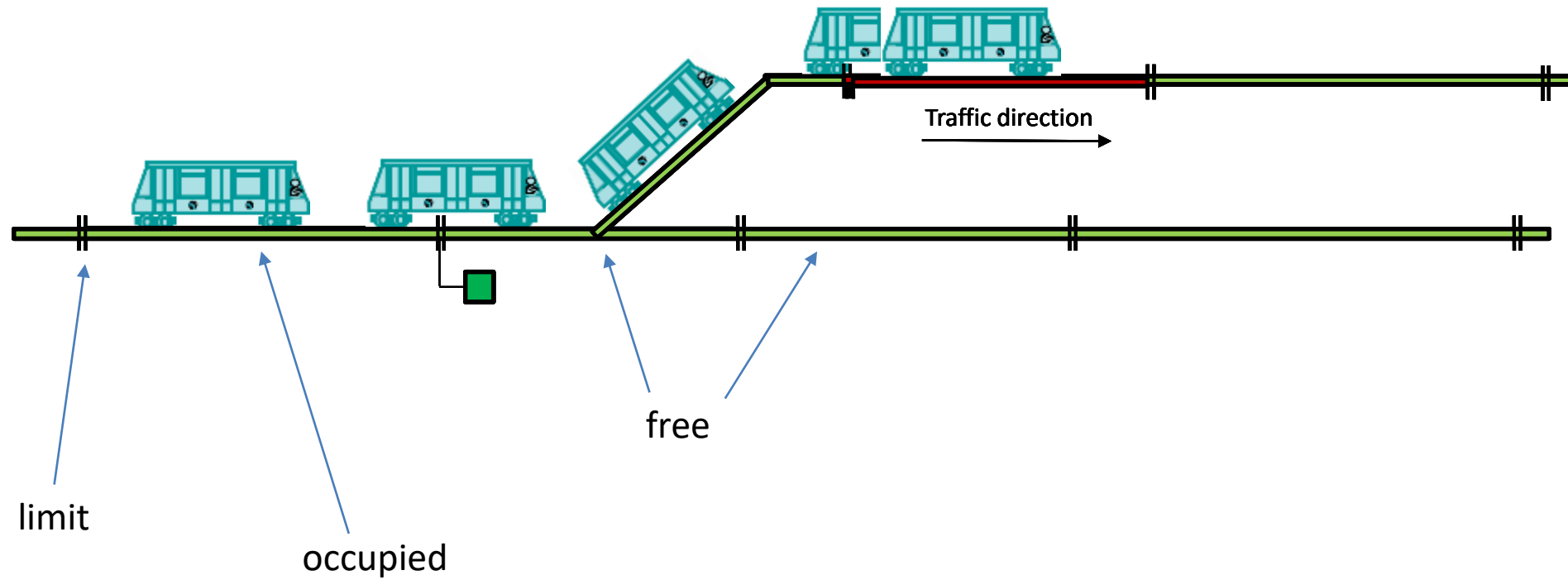
≡ Informed guess: interlocking protection zones involve track circuits.

## Example: track circuit backup

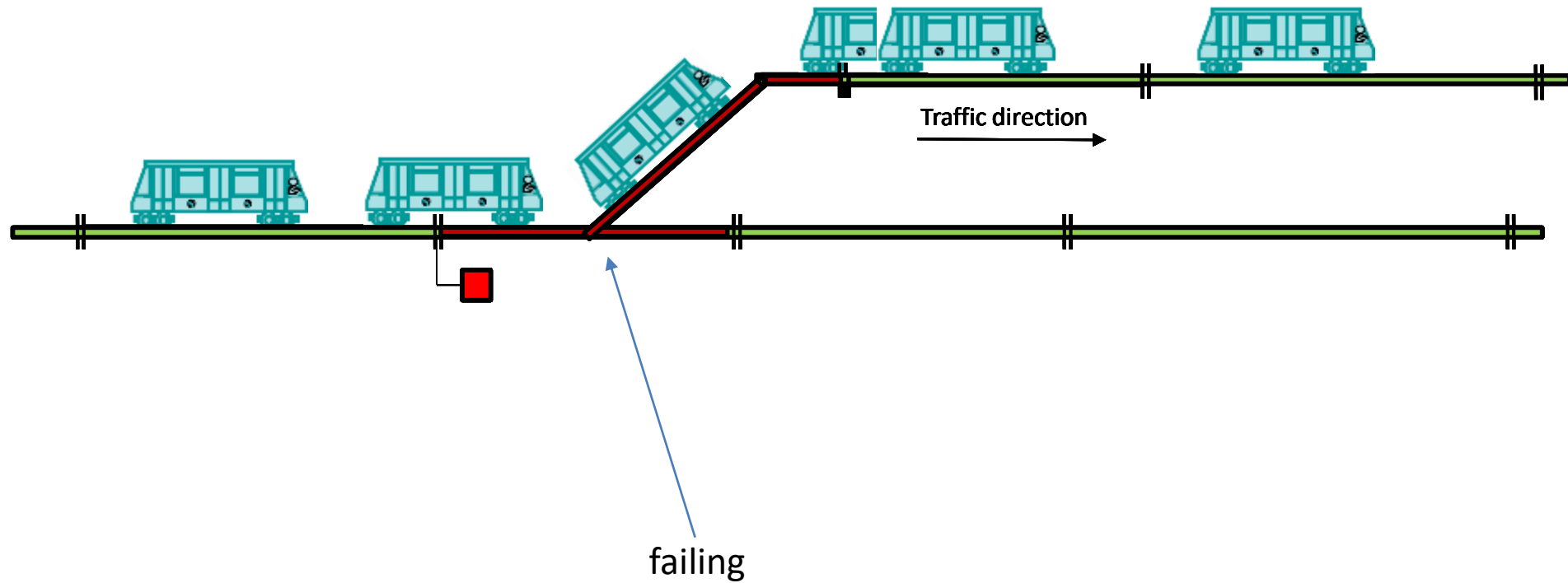


- ≡ It is our duty to inform interlocking experts that track circuit behavior is changed.
- ≡ Interlocking cannot rely on the classical physical properties of track circuits to guarantee its protection zones.
- ≡ First contribution: identify and prove properties on track circuits that we estimate sufficient for interlocking experts to guarantee the protection zones.
  - ▶ in collaboration with an interlocking expert
- ≡ Second contribution: find the argument establishing these properties hold.
  - ▶ formalize it and prove its correctness.

# Scenario without track circuit backup



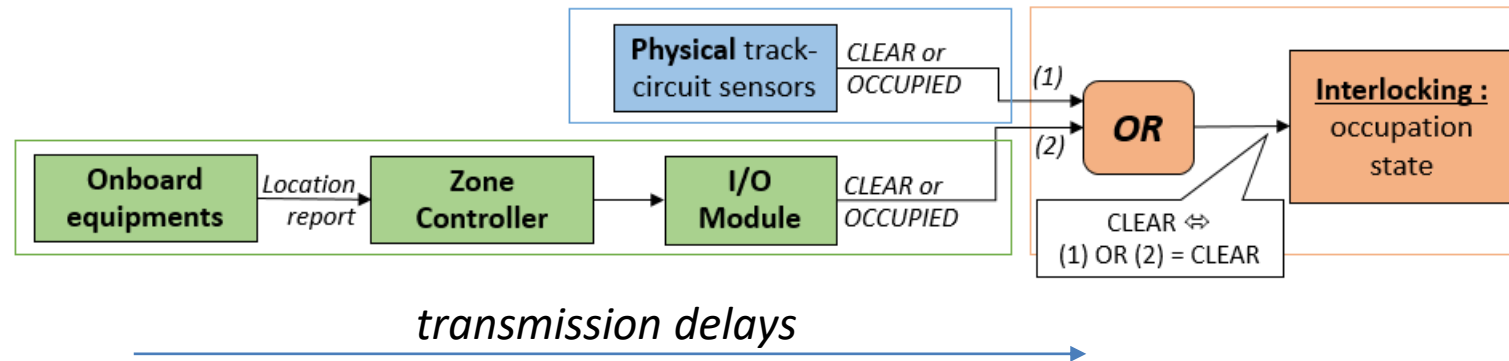
# Scenario with track circuit failure



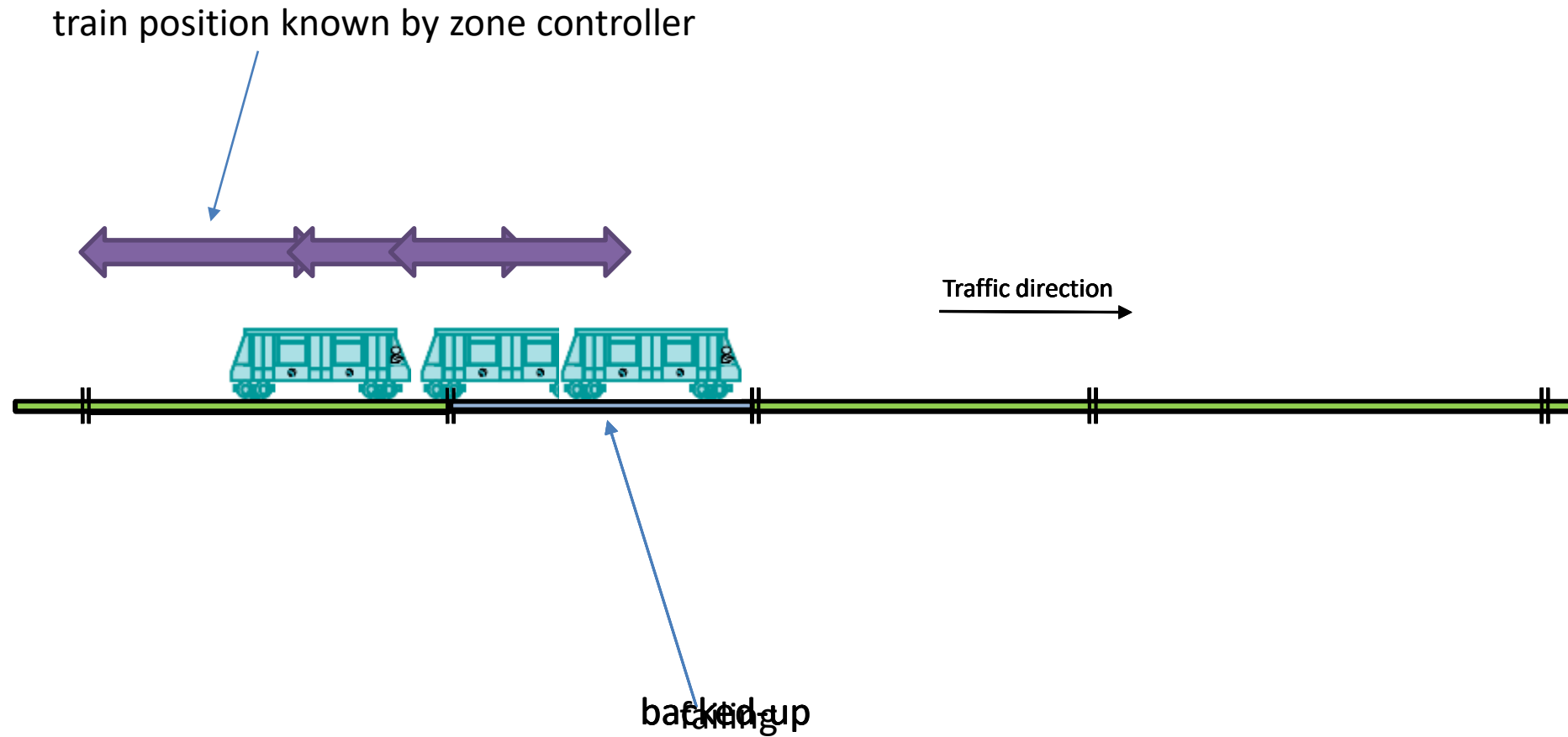
# Track circuit backup: definition



- ≡ CBTC tracks equipped trains based on location messages they send.
- ≡ CBTC tracks other trains based on track circuits and other detection devices.
- ≡ In case of failure, the CBTC can supply track circuit occupation to interlocking.



- ≡ Issue: the output of this function can be delayed compared to a direct connection between the track circuit and interlocking.



≡ Contribution: identify and prove properties on track circuits that we estimate sufficient for interlocking experts to guarantee the protection zones.

≡ Property guaranteed by the CBTC:

When a train circulates on an oriented track portion covered by a set of track circuits, there exists continuously a so-called « trailing track circuit » such that

- the output to interlocking is occupied;
- the tail of train is downstream the area covered by this track circuit.

≡ The argument identifies hypotheses sufficient for this property to be true:

- ▶ trains: minimal length, maximal speed of trains
- ▶ train localisation: precision, freshness threshold for train localisation
- ▶ track circuits: delay for the (physical) liberation, gap of shunt
- ▶ etc.

≡ Hypotheses provide equations between those parameters.

- ▶ Reusability: parameters vary line to line.



≡ Scenarios play a fundamental role

- ▶ *Exploratory* scenarios to acquire domain expertise
- ▶ *Explanatory* scenarios to justify hypotheses

≡ The validation of proof mechanisms by Event-B is *fruitful* to uncover corner cases.

≡ We do *not* model the whole CBTC in Event-B:

- ▶ one proof mechanism (property) at a time
  - ▶ only the aspects relevant for a given proof mechanism (property)
- ☛ *lean models*

≡ We are able to extract and state a set of hypotheses sufficient to establish a given property.

- ▶ We estimate this is the main benefit of this work
- ▶ We identify possibly superfluous safety requirements in the input document

- ≡ Interaction with expert domains is of paramount importance.
  - ▶ The proof mechanism reflects the know-how and know-why of the system designers
  - ▶ Clarifications; validation of hypotheses
  
- ≡ The necessity to build a proof emphasizes the importance of some mechanisms that have greater consequences on safety than one could think... (track circuit backup).
  
- ≡ The safety analysis team must be seen as constructive by the design team.
  
- ≡ Performing safety analysis during the design phase would seem to be more effective.
  - ▶ Sharing of arguments between teams.
  - ▶ Optimization of sub-system requirements.

- ≡ The properties of objects involved in our sufficient hypotheses can be used for *data validation* on the lines where Octys is deployed.
- ≡ Use as a *theory (trailing track circuit, protection zones...)* for future evolutions of Octys or similar products.
- ≡ Sub-system properties are requirements for sub-system suppliers.
  - ▶ Their formalization could be used as *proof goals* for the sub-systems.

# Safety Analysis of CBTC System: A Risk-Based Approach

## Event-B

Questions?

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- ≡ Top-level model identifies the interplay between Octys and interlocking with respect to the safety properties
  - ▶ interlocking hypotheses are terminal: to be validated by experts
  - ▶ other hypotheses are non-terminal: require specific arguments
  
- ≡ Hierarchical decomposition guided by the properties the protection zones have to comply with.
  
- ≡ Results in a collection of safety arguments addressing different target properties.

- ≡ *Property-guided* analysis of the system
  - ≠ sequential inspection of the specification
- ≡ Properties are expressed unambiguously.
- ≡ Terminal hypotheses are validated by third-party experts.
- ≡ Non-terminal hypotheses are subject to dedicated rigorous safety arguments.
- ≡ Domain experts review the proof mechanism and validate it matches the actual system.
- ≡ Tools are used to check the proof mechanism is logically sound.

- ≡ Each safety argument is delivered in a dedicated Word document.
- ≡ The document addresses a *single* property.
- ≡ The document collects all the *hypotheses* needed in the safety argument for this property.
- ≡ The full *proof mechanism* establishing the safety argument is described.
- ≡ The *formalization* of the proof mechanism in Event-B is also included in the document.

- ≡ Use of formalization by designers as a *theory of protection zones* to support future evolutions of Octys.
- ≡ Some terminal hypotheses could be target rules for *data validation* on the lines where Octys is deployed.
- ≡ Sub-system properties are requirements for sub-system suppliers.
  - ▶ Their formalization could be used as *proof goals* for the sub-systems.



- ▶ absence of collisions (front, side and rear)
- ▶ absence of derailments over uncontrolled switches

≡ Goal: prove safety properties

≡ Approach: build rigorous proof mechanisms (= arguments)

▶ readable by anyone familiar with the domain of application

▶ CBTC

≡ *Proof mechanism* = demonstration based on formal hypotheses

▶ desired property is stated clearly

▶ *demonstration*: logical proof expressed in natural language and checked with tools

▶ *hypothesis* = mathematical assumption

- justified: presentation of a catastrophic scenario when hypothesis is not met

- *non-terminal*: require other argument

- *terminal*:

- subsystem requirement found in the input documents

- missing information, accepted after validation by expert

- physical property